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When the war ended on August 15, 1945, I was a naval engineering cadet at the Kure Navy Yard near Hiroshima, Japan. A week later, I was demobilized and returned to my home in Tokyo, fortunate not to find it ravaged by firebombing. At the beginning of September, a large contingent of the American occupation forces led by General Douglas MacArthur moved its base from Yokohama to Tokyo. Near my home I watched a procession of American military motor vehicles snaking along Highway 1. This truly awe-inspiring cavalcade included jeeps, two-and-a-half-ton trucks, and enormous trailers mounted with tanks and artillery. At the time, I was a 21-year-old student in the Machinery Section of Engineering at the Tokyo Imperial University. Watching that magnificent parade of military vehicles, I was more than impressed by the gap in industrial strength between Japan and the U. S. That realization led me to devote my whole life to the

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development of the Japanese auto industry. I wrote a small article concerning this incident in Nikkei Sangyo Shimbun (one of the leading business newspapers in Japan) on May 2, 1983. The English translation of this story was carried in the July 3, 1983 edition of the Topeka Capital-Journal and the September 13, 1983 issue of the Asian Wall Street Journal. The Topeka Capital-Journal headline read, "MacArthur's Jeeps Were the Toyota Catalyst.

An in depth examination of manufacturing control systems using structured design methods. Topics include ladder logic and other IEC 61131 standards, wiring, communication, analog IO, structured programming, and communications. Allen Bradley PLCs are used extensively through the book, but the formal design methods are applicable to most other PLC brands. A full version of the book and other materials are available on-line at <http://engineeronadisk.com>

Multi-time author and well-regarded performance engine builder/designer John Baechtel has assembled the relevant mathematics and packaged it all together in a book designed for automotive enthusiasts. This book walks readers through the complete engine, showcasing the methodology required to define each specific parameter, and how to translate the engineering math to hard measurements reflected in various engine parts. Designing the engine to work as a system of related components is no small task, but the ease with which Baechtel escorts the reader through the process makes this book perfect for both the budding engine enthusiast and the professional builder.

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Finally, here is a single volume containing all of the engineering information needed to successfully design and implement any type of wireless network! Author Dan Dobkin covers every aspect of RF engineering necessary for wireless networks. He begins with a review of essential math and electromagnetic theory followed by thorough discussions of multiplexing, modulation types, bandwidth, link budgets, network concepts, radio system architectures, RF amplifiers, mixers and frequency conversion, filters, single-chip radio systems, antenna theory and designs, signal propagation, as well as planning and implementing wireless networks for both indoor and outdoor environments. The appendices contain such vital data as U.S., European, and Japanese technical and regulatory standards for wireless networks, measurements in wireless networks, reflection and matching of transmission lines, determining power density, and much more. No matter what type of wireless network you design—Bluetooth, UWB, or even metropolitan area network (MAN)—this book is the one reference you can't do without! The A-to-Z guide to wireless network engineering—covers everything from basic electromagnetic theory to modulation techniques to network planning and implementation! Engineering and design principles covered are applicable to any type of wireless network, including 802.11, 802.16, 802.20, and Bluetooth. Discusses state-of-the-art modulation techniques such as ultra wideband (UWB) and orthogonal frequency-division multiplexing (OFDM).

The advance in robotics has boosted the application of autonomous vehicles to perform tedious and risky tasks or to be cost-effective substitutes for their - man counterparts. Based on their working environment, a rough classification of the autonomous vehicles would include unmanned aerial vehicles (UAVs), - manned ground vehicles (UGVs), autonomous underwater vehicles (AUVs), and autonomous surface vehicles

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(ASVs). UAVs, UGVs, AUVs, and ASVs are called UVs (unmanned vehicles) nowadays. In recent decades, the development of - manned autonomous vehicles have been of great interest, and different kinds of autonomous vehicles have been studied and developed all over the world. In part- ular, UAVs have many applications in emergency situations; humans often cannot come close to a dangerous natural disaster such as an earthquake, a ood, an active volcano, or a nuclear disaster. Since the development of the rst UAVs, research efforts have been focused on military applications. Recently, however, demand has arisen for UAVs such as aero-robotsand ying robots that can be used in emergency situations and in industrial applications. Among the wide variety of UAVs that have been developed, small-scale HUAVs (helicopter-based UAVs) have the ability to take off and land vertically as well as the ability to cruise in ight, but their most important capability is hovering. Hoveringat a point enables us to make more eff- tive observations of a target. Furthermore, small-scale HUAVs offer the advantages of low cost and easy operation.

This book describes the latest advances in fuzzy logic, neural networks, and optimization algorithms, as well as their hybrid intelligent combinations, and their applications in the areas such as intelligent control, robotics, pattern recognition, medical diagnosis, time series prediction, and optimization. The topic is highly relevant as most current intelligent systems and devices use some form of intelligent feature to enhance their performance. The book also presents new and advanced models and algorithms of type-2 fuzzy logic and intuitionistic fuzzy systems, which are of great interest to researchers in these areas. Further, it proposes novel, nature-inspired optimization algorithms and innovative neural models. Featuring contributions on theoretical aspects as well as applications, the book appeals to a wide audience.

Control Systems Engineering, 7th Edition has become the top selling text for this course. It takes a practical

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approach, presenting clear and complete explanations. Real world examples demonstrate the analysis and design process, while helpful skill assessment exercises, numerous in-chapter examples, review questions and problems reinforce key concepts. A new progressive problem, a solar energy parabolic trough collector, is featured at the end of each chapter. This edition also includes Hardware Interface Laboratory experiments for use on the MyDAQ platform from National Instruments. A tutorial for MyDAQ is included as Appendix D.

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